$\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

#### The $H_3$ integrable system

Marcos A. G. García

(Collaboration with A. Turbiner)

#### Instituto de Ciencias Nucleares, UNAM, México August 10, 2010

イロト イヨト イヨト イヨト

 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

#### Rational integrable systems

- The Hamiltonian Reduction method provides an opportunity to construct non-trivial multidimensional completely integrable quantum Hamiltonians.
- These Hamiltonians are associated to the root spaces of the classical  $(A_n, B_n, C_n, D_n)$  and exceptional  $(G_2, F_4, E_{6,7,8})$  Lie algebras
- In the case of rational potentials one can also construct Hamiltonians associated with the noncrystallographic systems H<sub>3</sub>, H<sub>4</sub> and l<sub>2</sub>(m) (Olshanestky-Perelomov, '75)

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

#### Rational integrable systems

- The Hamiltonian Reduction method provides an opportunity to construct non-trivial multidimensional completely integrable quantum Hamiltonians.
- These Hamiltonians are associated to the root spaces of the classical (*A<sub>n</sub>*, *B<sub>n</sub>*, *C<sub>n</sub>*, *D<sub>n</sub>*) and exceptional (*G*<sub>2</sub>, *F*<sub>4</sub>, *E*<sub>6,7,8</sub>) Lie algebras
- In the case of rational potentials one can also construct Hamiltonians associated with the noncrystallographic systems H<sub>3</sub>, H<sub>4</sub> and l<sub>2</sub>(m) (Olshanestky-Perelomov, '75)

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

### Rational integrable systems

- The Hamiltonian Reduction method provides an opportunity to construct non-trivial multidimensional completely integrable quantum Hamiltonians.
- These Hamiltonians are associated to the root spaces of the classical (*A<sub>n</sub>*, *B<sub>n</sub>*, *C<sub>n</sub>*, *D<sub>n</sub>*) and exceptional (*G*<sub>2</sub>, *F*<sub>4</sub>, *E*<sub>6,7,8</sub>) Lie algebras
- In the case of rational potentials one can also construct Hamiltonians associated with the noncrystallographic systems  $H_3$ ,  $H_4$  and  $I_2(m)$  (Olshanestky-Perelomov, '75)

・ロット (雪) (日) (日)

 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces

Integral

- Algebraic expressions of quantum Hamiltonians for all crystallographic root systems have been found for both rational and trigonometric cases (A. Turbiner et al., 1997 -2009)
- The eigenfunctions can be obtained explicitly as polynomials
- The spectrum can be found in a closed form as a polynomial in the quantum numbers

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

- Algebraic expressions of quantum Hamiltonians for all crystallographic root systems have been found for both rational and trigonometric cases (A. Turbiner et al., 1997 -2009)
- The eigenfunctions can be obtained explicitly as polynomials
- The spectrum can be found in a closed form as a polynomial in the quantum numbers

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

- Algebraic expressions of quantum Hamiltonians for all crystallographic root systems have been found for both rational and trigonometric cases (A. Turbiner et al., 1997 -2009)
- The eigenfunctions can be obtained explicitly as polynomials
- The spectrum can be found in a closed form as a polynomial in the quantum numbers

Rational integrable systems The *H*<sub>3</sub> rational model Algebraic form Invariant polynomial spaces

The Hamiltonian in the rational case is

$$\mathcal{H}_{\Delta} = \frac{1}{2} \sum_{k=1}^{N} \left[ -\frac{\partial^2}{\partial x_k^2} + \omega^2 x_k^2 \right] + \frac{1}{2} \sum_{\alpha \in \mathcal{R}_+} g_{|\alpha|} |\alpha|^2 \frac{1}{(\alpha \cdot x)^2}$$

Integral

- $\mathcal{R}_+$  = set of positive roots in the system  $\Delta$ , rank( $\Delta$ ) = N
- $\omega \in \mathbf{R}$  a parameter
- g<sub>|α|</sub> coupling constants depending on the root length
  x = (x<sub>1</sub>, x<sub>2</sub>,..., x<sub>N</sub>)

Configuration space is the subspace of  $\mathbf{R}^N$  where

$$(\alpha \cdot x) > 0$$

for any  $\alpha \in \mathcal{R}_+$ 

・ロト ・日 ・ ・ 日 ・ ・ 日 ・

 Rational integrable systems

 The H3 rational model

 Algebraic form

 Invariant polynomial spaces

 Integral

The Hamiltonian in the rational case is

$$\mathcal{H}_{\Delta} = \frac{1}{2} \sum_{k=1}^{N} \left[ -\frac{\partial^2}{\partial x_k^2} + \omega^2 x_k^2 \right] + \frac{1}{2} \sum_{\alpha \in \mathcal{R}_+} g_{|\alpha|} |\alpha|^2 \frac{1}{(\alpha \cdot x)^2}$$

•  $\mathcal{R}_+$  = set of positive roots in the system  $\Delta$ , rank( $\Delta$ ) = N

• 
$$\omega \in \mathbf{R}$$
 a parameter

•  $g_{|\alpha|}$  coupling constants depending on the root length •  $x = (x_1, x_2, \dots, x_N)$ 

Configuration space is the subspace of  $\mathbf{R}^N$  where

$$(\alpha \cdot x) > 0$$

for any  $\alpha \in \mathcal{R}_+$ 

#### Rational integrable systems

The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

#### The goal is

 To find a transformation x → τ leading to algebraic form of the Hamiltonian (if exists)

$$h_{\Delta} = \sum_{i,j=1}^{N} A_{ij}(\tau) rac{\partial^2}{\partial au_i \partial au_j} + \sum_{j=1}^{N} B_j(\tau) rac{\partial}{\partial au_j} \; ,$$

where  $A_{ij}( au)$ ,  $B_j( au)$  are polynomials

イロト イヨト イヨト イヨト

E

 The H3 integrable model
 Rational integrable systems

 The h<sup>(3)</sup> algebra
 The H3 integrable model

 The discrete H3 system
 Algebraic form

 Quasi-exactly-solvable generalization
 Invariant polynomial spaces

 Conclusion
 Integral

• Find finite-dimensional invariant spaces for  $h_{\Delta}$  of a form

 $\mathcal{P}_n^{\alpha} = \langle \tau_1^{p_1} \tau_2^{p_2} \dots \tau_r^{p_r} | 0 \le \alpha_1 p_1 + \alpha_2 p_2 + \dots + \alpha_r p_r \le n \rangle ,$ (if exist) for

$$n = 0, 1, 2, \ldots$$
  $\alpha_1, \alpha_2, \ldots, \alpha_r \in \mathbf{Z}^+$ 

They are classified by characteristic vector

$$\boldsymbol{\alpha} = (\alpha_1, \alpha_2, \ldots, \alpha_r)$$

• These spaces can be ordered by inclusion:

 $\mathcal{P}_0 \subset \mathcal{P}_1 \subset \mathcal{P}_2 \subset \cdots \subset \mathcal{P}_n \subset \cdots$ 

Such an object is called an *infinite flag* 

 The H3 integrable model
 Rational integrable systems

 The h<sup>(3)</sup> algebra
 The H3 integrable model

 The discrete H3 system
 Algebraic form

 Quasi-exactly-solvable generalization
 Invariant polynomial spaces

 Conclusion
 Integral

• Find finite-dimensional invariant spaces for  $h_{\Delta}$  of a form

 $\mathcal{P}_n^{\alpha} = \langle \tau_1^{p_1} \tau_2^{p_2} \dots \tau_r^{p_r} | 0 \le \alpha_1 p_1 + \alpha_2 p_2 + \dots + \alpha_r p_r \le n \rangle ,$ (if exist) for

$$n = 0, 1, 2, \ldots$$
  $\alpha_1, \alpha_2, \ldots, \alpha_r \in \mathbf{Z}^+$ 

They are classified by characteristic vector

$$\boldsymbol{\alpha} = (\alpha_1, \alpha_2, \ldots, \alpha_r)$$

• These spaces can be ordered by inclusion:

$$\mathcal{P}_0 \subset \mathcal{P}_1 \subset \mathcal{P}_2 \subset \cdots \subset \mathcal{P}_n \subset \cdots$$

Such an object is called an *infinite flag* 

・ロット (雪) (日) (日)

Rational integrable systems **The** H<sub>3</sub> **rational model** Algebraic form Invariant polynomial spaces Integral

#### The $H_3$ rational model

The  $H_3$  rational Hamiltonian is

$$\begin{aligned} \mathcal{H} &= \frac{1}{2} \sum_{k=1}^{3} \left[ -\frac{\partial^2}{\partial x_k^2} + \omega^2 x_k^2 + \frac{g}{x_k^2} \right] \\ &+ \sum_{\{i,j,k\}} \sum_{\mu_{1,2}=0,1} \frac{2g}{[x_i + (-1)^{\mu_1} \varphi_+ x_j + (-1)^{\mu_2} \varphi_- x_k]^2} \end{aligned}$$

where  $\{i, j, k\} = \{1, 2, 3\}$  and all even permutations. The coupling constant is

$$g=
u(
u-1)>-rac{1}{4}$$

and

$$\varphi_{\pm} = \frac{1 \pm \sqrt{5}}{2}$$

The H<sub>3</sub> integrable system

# $\begin{array}{c} {\mbox{The $H_3$ integrable model} \\ {\mbox{The $h^{(3)}$ algebra} \\ {\mbox{The discrete $H_3$ system} \\ {\mbox{Quasi-exactly-solvable generalization} \\ {\mbox{Conclusion} } \end{array}$

Rational integrable systems **The** H<sub>3</sub> **rational model** Algebraic form Invariant polynomial spaces Integral

Explicitly:

$$\begin{aligned} \mathcal{H} &= -\frac{1}{2}\Delta^{(3)} + \frac{1}{2}\omega^2(x_1^2 + x_2^2 + x_3^2) + \frac{1}{2}\nu(\nu - 1)\left[\frac{1}{x_1^2} + \frac{1}{x_2^2} + \frac{1}{x_3^2}\right] \\ &+ 2\nu(\nu - 1)\left[\frac{1}{(x_1 + \varphi_+ x_2 + \varphi_- x_3)^2} + \frac{1}{(x_1 - \varphi_+ x_2 + \varphi_- x_3)^2} + \frac{1}{(x_1 - \varphi_+ x_2 - \varphi_- x_3)^2} + \frac{1}{(x_2 - \varphi_+ x_3 + \varphi_- x_1)^2} + \frac{1}{(x_2 - \varphi_+ x_3 + \varphi_- x_1)^2} + \frac{1}{(x_2 - \varphi_+ x_3 - \varphi_- x_1)^2} + \frac{1}{(x_3 - \varphi_+ x_1 + \varphi_- x_2)^2} + \frac{1}{(x_3 - \varphi_+ x_1 - \varphi_- x_2)^2} + \frac{1}{(x_3 - \varphi_+ x_1 - \varphi_- x_2)^2} + \frac{1}{(x_3 - \varphi_+ x_1 - \varphi_- x_2)^2} \end{aligned}$$

Marcos A. G. García The H<sub>3</sub> integrable system

・ロト ・回ト ・ヨト ・ヨト

Э

DQC

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

The Hamiltonian is invariant wrt the  $H_3$  Coxeter group, which is the full symmetry group of the icosahedron.

The Hamiltonian is symmetric with respect to the transformation

 $\begin{array}{c} x_i \longleftrightarrow x_j \\ \varphi_+ \longleftrightarrow \varphi_- \end{array}$ 

イロト イポト イヨト イヨト 三日

Rational integrable systems **The** H<sub>3</sub> **rational model** Algebraic form Invariant polynomial spaces Integral

The ground state function and its eigenvalue are

$$\Psi_0 = \Delta_1^{\nu} \Delta_2^{\nu} \exp\left(-\frac{\omega}{2} \sum_{k=1}^3 x_k^2\right) \ , \quad E_0 = \frac{3}{2} \omega (1+10\nu)$$

where

$$\begin{split} \Delta_1 &= \prod_{k=1}^3 x_k \\ \Delta_2 &= \prod_{\{i,j,k\}} \prod_{\mu_{1,2}=0,1} \left[ x_i + (-1)^{\mu_1} \varphi_+ x_j + (-1)^{\mu_2} \varphi_- x_k \right] \end{split}$$

イロト イヨト イヨト イヨト

E

 The H3 integrable model
 Rational integrable systems

 The h<sup>(3)</sup> algebra
 The H3 rational model

 The discrete H3 system
 Algebraic form

 Quasi-exactly-solvable generalization
 Invariant polynomial spaces

 Conclusion
 Integral

Explicitly:

$$\begin{split} \Psi_{0} &= \left[ x_{1} \ x_{2} \ x_{3} \right]^{\nu} \ \times \\ &\left[ \left( x_{1} + \varphi_{+} x_{2} + \varphi_{-} x_{3} \right) \left( x_{1} - \varphi_{+} x_{2} + \varphi_{-} x_{3} \right) \left( x_{1} + \varphi_{+} x_{2} - \varphi_{-} x_{3} \right) \right. \\ &\left. \left( x_{1} - \varphi_{+} x_{2} - \varphi_{-} x_{3} \right) \left( x_{2} + \varphi_{+} x_{3} + \varphi_{-} x_{1} \right) \left( x_{2} - \varphi_{+} x_{3} + \varphi_{-} x_{1} \right) \right. \\ &\left. \left( x_{2} + \varphi_{+} x_{3} - \varphi_{-} x_{1} \right) \left( x_{2} - \varphi_{+} x_{3} - \varphi_{-} x_{1} \right) \left( x_{3} + \varphi_{+} x_{1} + \varphi_{-} x_{2} \right) \right. \\ &\left. \left( x_{3} - \varphi_{+} x_{1} + \varphi_{-} x_{2} \right) \left( x_{3} + \varphi_{+} x_{1} - \varphi_{-} x_{2} \right) \left( x_{3} - \varphi_{+} x_{1} - \varphi_{-} x_{2} \right) \right]^{\nu} \\ & \times \left. \exp \left[ - \frac{\omega}{2} \left( x_{1}^{2} + x_{2}^{2} + x_{3}^{2} \right) \right] \end{split}$$

・ロト ・ 日 ・ ・ ヨ ・ ・ ヨ ・

Э

DQC

 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems **The** H<sub>3</sub> **rational model** Algebraic form Invariant polynomial spaces Integral

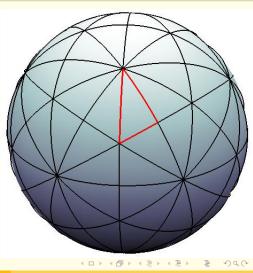
#### Configuration space

The configuration space is the domain in  $\mathbf{R}^3$  where  $x_{1,2,3} > 0$  bounded by the planes

$$x_1=0, \quad x_3=0,$$

$$x_3+\varphi_+x_1+\varphi_-x_2=0.$$

(the domain where  $(\alpha \cdot x) > 0$ ).



 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### The algebraic form of the Hamiltonian

Make a gauge rotation of the Hamiltonian:

$$h = -2(\Psi_0)^{-1}(\mathcal{H} - E_0)(\Psi_0)$$

New spectral problem arises

$$h\phi(x) = -2\epsilon\phi(x)$$

with spectral parameter  $\epsilon = E - E_0$ 

Can we find variables leading to an algebraic form of h?

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### The algebraic form of the Hamiltonian

Make a gauge rotation of the Hamiltonian:

$$h = -2(\Psi_0)^{-1}(\mathcal{H} - E_0)(\Psi_0)$$

New spectral problem arises

$$h\phi(x) = -2\epsilon\phi(x)$$

with spectral parameter  $\epsilon = E - E_0$ 

Can we find variables leading to an algebraic form of h?

 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

### What might those variables be? The invariants of the $H_3$ group

• Consider the fundamental weights of  $\Delta_{H_3}$  and their orbits  $\Omega$ :

weight vector	orbit size
$\omega_1=(0,arphi_+,1)$	12
$\omega_2=(1,\varphi_+^2,0)$	

Choose the shortest orbit and average

 $t_a(x) = \sum_{\alpha \in \Omega} (\omega \cdot x)^a$ 

a = 2, 6, 10 are the degrees of the  $H_3$  group

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

### What might those variables be? The invariants of the $H_3$ group

• Consider the fundamental weights of  $\Delta_{H_3}$  and their orbits  $\Omega$ :

weight vector	orbit size
$\omega_1=(0,arphi_+,1)$	12
$\omega_2=(1,\varphi_+^2,0)$	

Choose the shortest orbit and average

$$t_a(x) = \sum_{\omega \in \Omega_1} (\omega \cdot x)^a$$

a = 2, 6, 10 are the degrees of the  $H_3$  group

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

What might those variables be? The invariants of the  $H_3$  group

• Consider the fundamental weights of  $\Delta_{H_3}$  and their orbits  $\Omega$ :

weight vector	orbit size
$\omega_1=(0,arphi_+,1)$	12
$\omega_2=(1,arphi_+^2,0)$	20
$\omega_{3}=(0,2\varphi_{+},0)$	30

Choose the shortest orbit and average

$$t_a(x) = \sum_{\omega \in \Omega_1} (\omega \cdot x)^a$$

a = 2, 6, 10 are the degrees of the  $H_3$  group

I ∃ ≥

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

What might those variables be? The invariants of the  $H_3$  group

• Consider the fundamental weights of  $\Delta_{H_3}$  and their orbits  $\Omega$ :

weight vector	orbit size
$\omega_1=(0,arphi_+,1)$	12
$\omega_2=(1,arphi_+^2,0)$	20
$\omega_3=(0,2arphi_+,0)$	30

• Choose the shortest orbit and average

$$t_a(x) = \sum_{\omega \in \Omega_1} (\omega \cdot x)^a$$

a = 2, 6, 10 are the degrees of the  $H_3$  group

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

• The invariants are defined ambiguously

$$t_2 \longrightarrow t_2$$
  

$$t_6 \longrightarrow t_6 + \alpha_1 t_2^3$$
  

$$t_{10} \longrightarrow t_{10} + \alpha_2 t_2^2 t_6 + \alpha_3 t_2^5$$

- We look for parameters  $\alpha_i$  such that
  - ▶ the Hamiltonian *h* has algebraic form
  - ▶ has infinitely-many invariant subspaces in polynomials
  - ▶ these subspaces form a flag
  - ▶ the flag is "minimal"

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

• The invariants are defined ambiguously

$$t_2 \longrightarrow t_2$$
  

$$t_6 \longrightarrow t_6 + \alpha_1 t_2^3$$
  

$$t_{10} \longrightarrow t_{10} + \alpha_2 t_2^2 t_6 + \alpha_3 t_2^5$$

- We look for parameters  $\alpha_i$  such that
  - $\blacktriangleright$  the Hamiltonian h has algebraic form
  - ▶ has infinitely-many invariant subspaces in polynomials
  - ► these subspaces form a flag
  - ► the flag is "minimal"

# $\begin{array}{c} {\mbox{The $H_3$ integrable model}}\\ {\mbox{The $h^{(3)}$ algebra}}\\ {\mbox{The discrete $H_3$ system}\\ {\mbox{Quasi-exactly-solvable generalization}}\\ {\mbox{Conclusion}} \end{array}$

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### Those variables are

$$\begin{aligned} \tau_1 &= \frac{1}{10 + 2\sqrt{5}} t_2 \\ \tau_2 &= \frac{1}{10 + 16\sqrt{5}} \left( t_6 - \frac{13}{10} t_2^3 \right) \\ \tau_3 &= \frac{1}{250 + 110\sqrt{5}} \left( t_{10} - \frac{76}{15} t_2^2 t_6 + \frac{1531}{375} t_2^5 \right) \end{aligned}$$

Explicit expressions

The Hamiltonian takes the algebraic form

$$h = \sum_{i,j=1}^{3} A_{ij} \frac{\partial^2}{\partial \tau_i \partial \tau_j} + \sum_{j=1}^{3} B_j \frac{\partial}{\partial \tau_j}$$

Marcos A. G. García The H<sub>3</sub> integrable system

イロト イヨト イヨト イヨト

E

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

with

$$A_{11} = 4\tau_1$$

$$A_{12} = 12\tau_2$$

$$A_{13} = 20\tau_3$$

$$A_{22} = -\frac{48}{5}\tau_1^2\tau_2 + \frac{45}{2}\tau_3$$

$$A_{23} = \frac{16}{15}\tau_1\tau_2^2 - 24\tau_1^2\tau_3$$

$$A_{33} = -\frac{64}{3}\tau_1\tau_2\tau_3 + \frac{128}{45}\tau_2^3$$

$$B_1 = 6 + 60\nu - 4\omega\tau_1$$

$$B_2 = -\frac{48}{5}(1+5\nu)\tau_1^2 - 12\omega\tau_2$$

$$B_3 = -\frac{64}{15}(2+5\nu)\tau_1\tau_2 - 20\omega\tau_3$$

Marcos A. G. García

The H<sub>3</sub> integrable system

DQC

 $\begin{array}{c} \mbox{The $H_3$ integrable model} \\ \mbox{The $h^{(3)}$ algebra} \\ \mbox{The discrete $H_3$ system} \\ \mbox{Quasi-exactly-solvable generalization} \\ \mbox{Conclusion} \end{array}$ 

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### Configuration space and Jacobian

In  $\tau$ 's the configuration space boundary is an algebraic surface of degree 7 (degree 30 in x)

$$\begin{split} \kappa(\tau) &= -12960\tau_1^5\tau_3^2 + 5760\tau_1^4\tau_2^2\tau_3 - 640\tau_1^3\tau_2^4 - 54000\tau_1^2\tau_2\tau_3^2 \\ &+ 21600\tau_1\tau_2^3\tau_3 - 2304\tau_2^5 - 50625\tau_3^3 = 0 \end{split}$$

Boundary corresponds to zeros of  $\Psi_0$ 

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

The square of the Jacobian of the change of variables  $x \rightarrow \tau$  can be calculated explicitly:

$$J^{2} = \begin{vmatrix} \frac{\partial \tau_{1}}{\partial x_{1}} & \frac{\partial \tau_{1}}{\partial x_{2}} & \frac{\partial \tau_{1}}{\partial x_{3}} \\ \frac{\partial \tau_{2}}{\partial x_{1}} & \frac{\partial \tau_{2}}{\partial x_{2}} & \frac{\partial \tau_{2}}{\partial x_{3}} \\ \frac{\partial \tau_{3}}{\partial x_{1}} & \frac{\partial \tau_{3}}{\partial x_{2}} & \frac{\partial \tau_{3}}{\partial x_{3}} \end{vmatrix}^{2} = \frac{9}{5} \prod_{\alpha \in \mathcal{R}_{3}^{+}} (\alpha \cdot x)^{2} = \frac{8}{45} \kappa(\tau) .$$

It vanishes on the boundary of the configuration space.

・ロト ・回ト ・ヨト・

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### Polynomial spaces

The algebraic operator h preserves subspaces

$$\mathcal{P}_n^{(1,2,3)} = \langle \tau_1^{n_1} \tau_2^{n_2} \tau_3^{n_3} | 0 \le n_1 + 2n_2 + 3n_3 \le n \rangle \;, \quad n \in \mathbf{N}$$

 $\Rightarrow$  characteristic vector is (1,2,3), they form flag

The flag is invariant with respect to weighted-projective transformations:

$$\begin{aligned} \tau_1 &\longrightarrow \tau_1 + a \\ \tau_2 &\longrightarrow \tau_2 + b_1 \tau_1^2 + b_2 \tau_1 + b_3 \\ \tau_3 &\longrightarrow \tau_3 + c_1 \tau_1 \tau_2 + c_2 \tau_1^3 + c_3 \tau_2 + c_4 \tau_1^2 + c_5 \tau_1 + c_6 \end{aligned}$$

Rational integrable systems The H<sub>3</sub> rational model Algebraic form Invariant polynomial spaces Integral

#### Polynomial spaces

The algebraic operator h preserves subspaces

$$\mathcal{P}_n^{(1,2,3)} = \langle \tau_1^{n_1} \tau_2^{n_2} \tau_3^{n_3} | 0 \le n_1 + 2n_2 + 3n_3 \le n \rangle \;, \quad n \in \mathbf{N}$$

 $\Rightarrow$  characteristic vector is (1,2,3), they form flag

The flag is invariant with respect to weighted-projective transformations:

$$\tau_1 \longrightarrow \tau_1 + a$$
  

$$\tau_2 \longrightarrow \tau_2 + b_1 \tau_1^2 + b_2 \tau_1 + b_3$$
  

$$\tau_3 \longrightarrow \tau_3 + c_1 \tau_1 \tau_2 + c_2 \tau_1^3 + c_3 \tau_2 + c_4 \tau_1^2 + c_5 \tau_1 + c_6$$

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### Eigenfunctions and spectrum

One can find the spectrum of *h* explicitly:

$$\epsilon_{k_1,k_2,k_3} = 2\omega(k_1 + 3k_2 + 5k_3) , \quad k_i = 0, 1, 2, \dots$$

Degeneracy:  $k_1 + 3k_2 + 5k_3 = \text{integer}$ 

The energies of the original Hamiltonian are

$$E = E_0 + \epsilon$$

Eigenfunctions  $\phi_{n,i}$  of *h* are elements of  $\mathcal{P}_n^{(1,2,3)}$ . Eigenfunctions of  $\mathcal{H}$  are

$$\Psi = \Psi_0 \phi$$
 (factorization)

・ロト ・日下・ ・ ヨト・

 The H<sub>3</sub> integrable model
 Rational integrable systems

 The h<sup>(3)</sup> algebra
 The H<sub>3</sub> rational model

 The discrete H<sub>3</sub> system
 Algebraic form

 Quasi-exactly-solvable generalization
 Invariant polynomial spaces

 Conclusion
 Integral

•  $\mathbf{n} = \mathbf{0}$ :  $\phi_{0,0} = 1$ ,  $\epsilon_{0,0} = 0$ . •  $\mathbf{n} = \mathbf{1}$ :  $\phi_{1,0} = \tau_1 + \frac{3}{2\omega}(1+10\nu)$ ,  $\epsilon_{1,0} = 2\omega$ . •  $\mathbf{n} = \mathbf{2}$ :  $\phi_{2,0} = \tau_1^2 - \frac{5}{\omega}(1+6\nu)\tau_1 + \frac{15}{4\omega^2}(1+6\nu)(1+10\nu)$ ,  $\epsilon_{2,0} = 4\omega$ ,

$$\begin{split} \phi_{2,1} &= \tau_2 + \frac{12}{5\omega} (1+5\nu) \tau_1^2 - \frac{6}{\omega^2} (1+5\nu) (1+6\nu) \tau_1 \\ &+ \frac{3}{\omega^3} (1+5\nu) (1+6\nu) (1+10\nu) , \\ \epsilon_{2,1} &= 6\omega . \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system

Rational integrable systems The  $H_3$  rational model Algebraic form Invariant polynomial spaces Integral

#### Separation in spherical coordinates

In spherical coordinates the  $H_3$  Hamiltonian is

$$\mathcal{H}=-rac{1}{2}\Delta^{(3)}+rac{1}{2}\omega^2r^2+rac{W( heta,\phi)}{r^2}$$

The Schroedinger equation is separable:

$$\Psi(r, heta,\phi)=R(r)Q( heta,\phi)$$

with

$$\begin{bmatrix} -\frac{1}{2r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) + \frac{1}{2} \omega^2 r^2 + \frac{\gamma}{r^2} \end{bmatrix} R(r) = ER(r)$$

$$\begin{bmatrix} \frac{1}{2} \mathcal{L}^2 + W(\theta, \phi) \end{bmatrix} Q(\theta, \phi) = \gamma Q(\theta, \phi)$$

Marcos A. G. García

The  $H_3$  integrable system

The H <sub>3</sub> integrable model	Rational integrable systems
The h <sup>(3)</sup> algebra	The H <sub>3</sub> rational model
The discrete H <sub>3</sub> system	Algebraic form
Quasi-exactly-solvable generalization	Invariant polynomial spaces
Conclusion	Integral

The operator

$$\mathcal{F} = rac{1}{2} \mathcal{L}^2 + W(\theta, \phi)$$

• Explicit expression

is an integral of motion

$$[\mathcal{H},\mathcal{F}]=0$$

The gauge rotated operator

$$f = (\Psi_0)^{-1} (\mathcal{F} - \gamma_0) \Psi_0 \;, \quad \gamma_0 = rac{15}{2} 
u (1 + 15 
u)$$

has an algebraic form in  $\tau$ 's:

$$f = \sum_{i,j=2}^{3} F_{ij} \frac{\partial^2}{\partial \tau_i \partial \tau_j} + \sum_{j=2}^{3} G_j \frac{\partial}{\partial \tau_j}$$

Marcos A. G. García The H<sub>3</sub> integrable system

The H <sub>3</sub> integrable model	Rational integrable systems
The h <sup>(3)</sup> algebra	The H <sub>3</sub> rational model
The discrete H <sub>3</sub> system	Algebraic form
Quasi-exactly-solvable generalization	Invariant polynomial spaces
Conclusion	Integral

#### with

$$\begin{split} F_{22} &= \frac{24}{5} \tau_1^3 \tau_2 - \frac{45}{4} \tau_1 \tau_3 + 18 \tau_2^2 , \\ F_{23} &= -\frac{8}{15} \tau_1^2 \tau_2^2 + 12 \tau_1^3 \tau_3 + 30 \tau_2 \tau_3 , \\ F_{33} &= -\frac{64}{45} \tau_1 \tau_2^3 + \frac{32}{3} \tau_1^2 \tau_2 \tau_3 + 50 \tau_3^2 , \\ G_2 &= \frac{24}{5} (1 + 5\nu) \tau_1^3 + 3(7 + 30\nu) \tau_2 , \\ G_3 &= \frac{32}{15} (2 + 5\nu) \tau_1^2 \tau_2 + 5(11 + 30\nu) \tau_3 \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system

•

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

 The H3 integrable model
 Rational integrable systems

 The h<sup>(3)</sup> algebra
 The H3 rational model

 The discrete H3 system
 Algebraic form

 Quasi-exactly-solvable generalization
 Invariant polynomial spaces

 Conclusion
 Integral

The integral f preserves the flag of polynomials

$$\mathcal{P}_{n}^{(1,3,5)} = \langle \tau_{1}^{n_{1}} \tau_{2}^{n_{2}} \tau_{3}^{n_{3}} | 0 \le n_{1} + 3n_{2} + 5n_{3} \le n \rangle$$

hence characteristic vector is (1,3,5). The operator *h* also preserves this flag.

Joint eigenfunctions belong to this flag !

Existence of the flag (1,2,3) may be related to degeneracy of  $\mathcal H$ 

イロト イポト イヨト イヨト

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イヨト イヨト イヨト

# The $h^{(3)}$ algebra.

Can  $\mathcal{P}_n^{(1,2,3)}$  be finite-dimensional representation spaces of a Lie algebra of differential operators? Yes

We call this algebra  $h^{(3)}$ . It is infinite-dimensional but finitely generated (30 operators).

- First class: *lowering and Cartan operators*, they act on  $\mathcal{P}_n$  at any *n*, infinite flag is preserved
- Second class: *raising operators*, a single space at a certain *n* is preserved

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イポト イヨト イヨト 二日

# The $h^{(3)}$ algebra.

Can  $\mathcal{P}_n^{(1,2,3)}$  be finite-dimensional representation spaces of a Lie algebra of differential operators? Yes

We call this algebra  $h^{(3)}$ . It is infinite-dimensional but finitely generated (30 operators).

- First class: *lowering and Cartan operators*, they act on  $\mathcal{P}_n$  at any *n*, infinite flag is preserved
- Second class: *raising operators*, a single space at a certain *n* is preserved

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イポト イヨト イヨト 二日

# The $h^{(3)}$ algebra.

Can  $\mathcal{P}_n^{(1,2,3)}$  be finite-dimensional representation spaces of a Lie algebra of differential operators? Yes

We call this algebra  $h^{(3)}$ . It is infinite-dimensional but finitely generated (30 operators).

- First class: *lowering and Cartan operators*, they act on  $\mathcal{P}_n$  at any *n*, infinite flag is preserved
- Second class: *raising operators*, a single space at a certain *n* is preserved

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イポト イヨト イヨト 二日

# The $h^{(3)}$ algebra.

Can  $\mathcal{P}_n^{(1,2,3)}$  be finite-dimensional representation spaces of a Lie algebra of differential operators? Yes

We call this algebra  $h^{(3)}$ . It is infinite-dimensional but finitely generated (30 operators).

- First class: *lowering and Cartan operators*, they act on  $\mathcal{P}_n$  at any *n*, infinite flag is preserved
- Second class: *raising operators*, a single space at a certain *n* is preserved

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イヨト イヨト イヨト

#### First order operators

The first class generators consist of 13 first order operators

$$\begin{split} T_{0}^{(1)} &= \partial_{1} , & T_{0}^{(2)} &= \partial_{2} , & T_{0}^{(3)} &= \partial_{3} , \\ T_{1}^{(1)} &= \tau_{1} \partial_{1} , & T_{2}^{(2)} &= \tau_{2} \partial_{2} , & T_{3}^{(3)} &= \tau_{3} \partial_{3} , \\ T_{1}^{(3)} &= \tau_{1} \partial_{3} , & T_{11}^{(3)} &= \tau_{1}^{2} \partial_{3} , & T_{111}^{(3)} &= \tau_{1}^{3} \partial_{3} , \\ T_{1}^{(2)} &= \tau_{1} \partial_{2} , & T_{11}^{(2)} &= \tau_{1}^{2} \partial_{2} , & T_{2}^{(3)} &= \tau_{2} \partial_{3} , \\ T_{12}^{(3)} &= \tau_{1} \tau_{2} \partial_{3} \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イヨト イヨト

### Second and third order operators

#### plus 6 second order generators

$$\begin{split} T_2^{(11)} &= \tau_2 \partial_{11} \,, \qquad T_{22}^{(13)} = \tau_2^2 \partial_{13} \,, \qquad T_{222}^{(33)} = \tau_2^3 \partial_{33} \,, \\ T_3^{(12)} &= \tau_3 \partial_{12} \,, \qquad T_3^{(22)} = \tau_3 \partial_{22} \,, \qquad T_{13}^{(22)} = \tau_1 \tau_3 \partial_{22} \,. \end{split}$$

and 2 third order generators

$$T_3^{(111)} = \tau_3 \partial_{111} , \qquad \qquad T_{33}^{(222)} = \tau_3^2 \partial_{222}$$

These 21 operators are generating elements of the flag-preserving subalgebra of  $h^{(3)}$ 

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イポト イヨト イヨト

## Second class (raising operators)

Define the auxiliary operator (which belongs to the first class)

$$J_0 = \tau_1 \partial_1 + 2\tau_2 \partial_2 + 3\tau_3 \partial_3 - n$$

Raising generators consist of 8 operators of 1<sup>st</sup>, 2<sup>nd</sup> and 3<sup>rd</sup> order

$$\begin{aligned} J_1^+ &= \tau_1 J_0 \,, & J_{2,-1}^+ &= \tau_2 \partial_1 J_0 \,, & J_{3,-2}^+ &= \tau_3 \partial_2 J_0 \,, \\ J_2^+ &= \tau_2 J_0 (J_0+1) \,, & J_{3,-11}^+ &= \tau_3 \partial_{11} J_0 \,, & J_{22,-3}^+ &= \tau_2^2 \partial_3 J_0 \,, \\ J_3^+ &= \tau_3 J_0 (J_0+1) (J_0+2) \,, & J_{3,-1}^+ &= \tau_3 \partial_1 J_0 (J_0+1) \end{aligned}$$

 $h^{(3)}$  is the infinite dimensional algebra of monomials in the 30 (22+8) generating elements

Flag preserving operators Raising operators **Commutation relations** The Hamiltonian in algebraic form

イロト イポト イヨト イヨト

## Subalgebras of $h^{(3)}$

Generating elements of  $h^{(3)}$  can be grouped in 10 Abelian subalgebras

$$\begin{split} L &= \{T_0^{(3)}, T_1^{(3)}, T_{11}^{(3)}, T_{111}^{(3)}\} &\longleftrightarrow \quad \mathfrak{L} = \{T_3^{(111)}, J_{3,-11}^+, J_{3,-1}^+, J_3^+\} \\ R &= \{T_0^{(2)}, T_1^{(2)}, T_{11}^{(2)}\} &\longleftrightarrow \quad \mathfrak{R} = \{T_2^{(11)}, J_{2,-1}^+, J_2^+\} \\ F &= \{T_2^{(3)}, T_{12}^{(3)}\} &\longleftrightarrow \quad \mathfrak{F} = \{T_3^{(12)}, J_{3,-2}^+\} \\ E &= \{T_{13}^{(22)}, T_3^{(22)}\} &\longleftrightarrow \quad \mathfrak{E} = \{T_{22}^{(13)}, J_{22,-3}^+\} \\ G &= \{T_{222}^{(33)}\} &\longleftrightarrow \quad \mathfrak{E} = \{T_{33}^{(222)}\} \end{split}$$

and a closed subalgebra

$$B = \{T_0^{(1)}, T_1^{(1)}, T_2^{(2)}, T_3^{(3)}, J_0, J_1^+\}$$

Flag preserving operators Raising operators **Commutation relations** The Hamiltonian in algebraic form

),

),

E

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

Commutation relations between commutative algebras:

[L,R]=0,	$[\mathfrak{L},\mathfrak{R}]=0,$
[L,F]=0,	$[\mathfrak{L},\mathfrak{F}]=0,$
$[L,E]=P_2(R),$	$[\mathfrak{L},\mathfrak{E}]=P_2(\mathfrak{R}),$
[L,G]=0,	$[\mathfrak{L},\mathfrak{G}]=0,$
[R,F]=L,	$[\mathfrak{R},\mathfrak{F}]=\mathfrak{L},$
[R,E]=0,	$[\mathfrak{R},\mathfrak{E}]=0,$
$[R,G]=P_2(F),$	$[\mathfrak{R},\mathfrak{G}]=P_2(\mathfrak{F}),$
$[F,E]=P_2(R\oplus B),$	$[\mathfrak{F},\mathfrak{E}]=P_2(\mathfrak{R}\oplus B)$
[F,G]=0,	$[\mathfrak{F},\mathfrak{G}]=0,$
$[E,G]=P_3(F\oplus B),$	$[\mathfrak{E},\mathfrak{G}]=P_3(\mathfrak{F}\oplus B)$

Flag preserving operators Raising operators **Commutation relations** The Hamiltonian in algebraic form

$$[L, \mathfrak{R}] = P_2(F \oplus B),$$
  

$$[L, \mathfrak{F}] = P_2(R \oplus B),$$
  

$$[L, \mathfrak{E}] = P_2(F),$$
  

$$[L, \mathfrak{E}] = P_2(R \oplus E),$$
  

$$[R, \mathfrak{F}] = E,$$
  

$$[R, \mathfrak{E}] = P_2(F \oplus B),$$
  

$$[R, \mathfrak{E}] = 0,$$
  

$$[F, \mathfrak{E}] = G,$$
  

$$[F, \mathfrak{E}] = P_2(E \oplus B),$$
  

$$[E, \mathfrak{E}] = 0,$$

$$\begin{split} [\mathfrak{L},R] &= P_2(\mathfrak{F} \oplus B), \\ [\mathfrak{L},F] &= P_2(\mathfrak{F} \oplus B), \\ [\mathfrak{L},E] &= P_2(\mathfrak{F}), \\ [\mathfrak{L},G] &= P_2(\mathfrak{F} \oplus \mathfrak{E}), \\ [\mathfrak{R},F] &= \mathfrak{E}, \\ [\mathfrak{R},E] &= P_2(\mathfrak{F} \oplus B), \\ [\mathfrak{R},G] &= 0, \\ [\mathfrak{F},G] &= \mathfrak{E}, \\ [\mathfrak{F},G] &= P_2(\mathfrak{E} \oplus B), \\ [\mathfrak{E},G] &= 0, \end{split}$$

◆□ > ◆□ > ◆臣 > ◆臣 > ○

Э

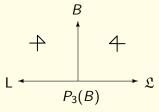
DQC

Flag preserving operators Raising operators **Commutation relations** The Hamiltonian in algebraic form

$$\begin{aligned} [L, \mathfrak{L}] &= P_3(B), \qquad [R, \mathfrak{R}] = P_2(B), \qquad [F, \mathfrak{F}] = P_2(B), \\ [E, \mathfrak{E}] &= P_3(B), \qquad [G, \mathfrak{G}] = P_4(B) \end{aligned}$$

Commutation relations between Abelian subalgebras and B:

 $[L,B] = L, \quad [R,B] = R, \quad [F,B] = F, \quad [E,B] = E, \quad [G,B] = G,$  $[\mathfrak{L},B] = \mathfrak{L}, \quad [\mathfrak{R},B] = \mathfrak{R}, \quad [\mathfrak{F},B] = \mathfrak{F}, \quad [\mathfrak{E},B] = \mathfrak{E}, \quad [\mathfrak{G},B] = \mathfrak{G}$ 



Flag preserving operators Raising operators **Commutation relations** The Hamiltonian in algebraic form

イロト イヨト イヨト イヨト

Э

#### Commutation relations between generators of B:

$$\begin{split} [T_0^{(1)}, T_1^{(1)}] &= T_0^{(1)} , \quad [T_0^{(1)}, T_2^{(2)}] = 0 , \qquad [T_0^{(1)}, T_3^{(3)}] = 0 , \\ [T_0^{(1)}, J_0] &= T_0^{(1)} , \qquad [T_0^{(1)}, J_1^+] = T_1^{(1)} + J_0 , \quad [T_1^{(1)}, T_2^{(2)}] = 0 , \\ [T_1^{(1)}, T_3^{(3)}] &= 0 , \qquad [T_1^{(1)}, J_0] = 0 , \qquad [T_1^{(1)}, J_1^+] = J_1^+ , \\ [T_2^{(2)}, T_3^{(3)}] &= 0 , \qquad [T_2^{(2)}, J_0] = 0 , \qquad [T_2^{(2)}, J_1^+] = 0 , \\ [T_3^{(3)}, J_0] &= 0 , \qquad [T_3^{(3)}, J_1^+] = 0 , \qquad [J_0, J_1^+] = J_1^+ \end{split}$$

Correspond to

 $B \cong g\ell_2 \oplus \mathcal{R}^{(2)}$ 

Flag preserving operators Raising operators Commutation relations The Hamiltonian in algebraic form

イロト イヨト イヨト イヨト

E

## The *h* Hamiltonian (Lie algebraic form)

#### Lie algebraic form for *h*:

$$\begin{split} h &= 4 \, T_1^{(1)} \, T_0^{(1)} + 24 \, T_2^{(2)} \, T_0^{(1)} + 40 \, T_3^{(3)} \, T_0^{(1)} - \frac{48}{5} \, T_2^{(2)} \, T_{11}^{(2)} \\ &+ \frac{45}{2} \, T_3^{(22)} + \frac{32}{15} \, T_{12}^{(3)} \, T_2^{(2)} - 48 \, T_3^{(3)} \, T_{11}^{(2)} - \frac{64}{3} \, T_3^{(3)} \, T_{12}^{(3)} \\ &+ \frac{128}{45} \, T_{222}^{(33)} + (6 + 60\nu) \, T_0^{(1)} - 4\omega \, T_1^{(1)} - \frac{48}{5} \, (1 + 5\nu) \, T_{11}^{(2)} \\ &- 12\omega \, T_2^{(2)} - \frac{64}{15} (2 + 5\nu) \, T_{12}^{(3)} - 20\omega \, T_3^{(3)} \end{split}$$

**Discrete** *H*<sub>3</sub> Hamiltonian

## Discrete $H_3$ system

The existence of the algebraic form of the Hamiltonian allows us to construct a discrete system with a property of isospectrality.

Let us introduce three pairs of finite difference operators

$$egin{aligned} \mathcal{D}_i^{(\delta_i)} &= rac{(e^{\delta_i \partial_i}-1)}{\delta_i} \;, \ \mathcal{X}_i^{(\delta_i)} &= ( au_i e^{-\delta_i \partial_i}) \;, \end{aligned}$$

where i = 1, 2, 3. They realize a three parametric canonical transformation in 3 + 3 phase space

$$[\mathcal{D}_i^{(\delta_i)}, \mathcal{D}_j^{(\delta_j)}] = 0 \ , \ [\mathcal{X}_i^{(\delta_i)}, \mathcal{X}_j^{(\delta_j)}] = 0 \ , \ [\mathcal{D}_i^{(\delta_i)}, \mathcal{X}_j^{(\delta_j)}] = \delta_{ij} \ .$$

イロト イポト イヨト イヨト

**Discrete** *H*<sub>3</sub> Hamiltonian

## Discrete $H_3$ system

The existence of the algebraic form of the Hamiltonian allows us to construct a discrete system with a property of isospectrality.

Let us introduce three pairs of finite difference operators

$$\mathcal{D}_i^{(\delta_i)} = rac{(e^{\delta_i \partial_i} - 1)}{\delta_i} \; , \ \mathcal{X}_i^{(\delta_i)} = (\tau_i e^{-\delta_i \partial_i}) \; ,$$

where i = 1, 2, 3. They realize a three parametric canonical transformation in 3 + 3 phase space

$$[\mathcal{D}_i^{(\delta_i)},\mathcal{D}_j^{(\delta_j)}]=0\;,\;[\mathcal{X}_i^{(\delta_i)},\mathcal{X}_j^{(\delta_j)}]=0\;,\;[\mathcal{D}_i^{(\delta_i)},\mathcal{X}_j^{(\delta_j)}]=\delta_{ij}\;.$$

イロト イポト イヨト イ

**Discrete** *H*<sub>3</sub> Hamiltonian

Take the linear differential operator  $\mathcal{L}(\partial_i, \tau_i)$ . Consider the eigenvalue problem

$$\mathcal{L}(\partial_i, \tau_i) \varphi(\tau) = \lambda \varphi(\tau)$$

with polynomial solutions

$$\varphi(\tau) = \sum \alpha_{klm} \tau_1^k \tau_2^l \tau_3^m$$

イロト イヨト イヨト イヨト

E

**Discrete** *H*<sub>3</sub> Hamiltonian

Performing the canonical transformation (discretization) we arrive at

$$\mathcal{L}(\mathcal{D}_i^{(\delta_i)},\mathcal{X}_i^{(\delta_i)}) arphi(\mathcal{X}_i^{(\delta_i)}) ert 0 
angle \ = \ \lambda arphi(\mathcal{X}_i^{(\delta_i)}) ert 0 
angle$$

One should introduce the vacuum  $|0\rangle$ :

$$\mathcal{D}_i^{(\delta_i)}|0
angle \ = \ 0 \ , \quad i=1,2,3. \qquad \Rightarrow \qquad |0
angle \equiv 1 \ .$$

The corresponding solutions are

$$\tilde{\varphi}(\tau) = \sum \alpha_{klm} \tau_1^{(k)} \tau_2^{(l)} \tau_3^{(m)} ,$$

where

$$au_i^{(n+1)} = au_i( au_i - \delta_i)( au_i - 2\delta_i)\cdots( au_i - n\delta_i)$$
 (quasi-monomial).

イロト イヨト イヨト イヨト

Performing the canonical discretization for the  $H_3$  Hamiltonian in the algebraic form  $h_{H_3}$  we arrive at the isospectral finite-difference operator

$$\tilde{h}_{H_3} \equiv h_{H_3}(\mathcal{D}_i^{(\delta_i)}, \mathcal{X}_i^{(\delta_i)}) = \sum_{k_1, k_2, k_3} A_{k_1, k_2, k_3} e^{k_1 \delta_1 \partial_1 + k_2 \delta_2 \partial_2 + k_3 \delta_3 \partial_3}$$

It is a 22-point finite-difference operator with the following non-vanishing coefficients

イロト イポト イヨト イヨト

 $\begin{array}{c} {\rm The} \ H_3 \ {\rm integrable \ model} \\ {\rm The} \ h^{(3)} \ {\rm algebra} \\ {\rm The \ } h^{\rm C3)} \ {\rm system} \\ {\rm Quasi-exactly-solvable \ generalization} \end{array}$ Conclusion

Discrete H<sub>3</sub> Hamiltonian

$$\begin{split} A_{0,0,0} &= -\frac{4}{\delta_1} (2+\delta_1 \omega) \left[ \frac{\tau_1}{\delta_1} + \frac{3\tau_2}{\delta_2} + \frac{5\tau_3}{\delta_3} \right] - \frac{6}{\delta_1} (1+10\nu) , \\ A_{1,0,0} &= \frac{2}{\delta_1} \left[ \frac{2\tau_1}{\delta_1} + \frac{12\tau_2}{\delta_2} + \frac{20\tau_3}{\delta_3} + 3(1+10\nu) \right] , \\ A_{-1,0,0} &= \frac{4}{\delta_1^2} (1+\delta_1 \omega) \tau_1 , \\ A_{-2,0,0} &= \frac{48}{5\delta_2} \tau_1 (\tau_1 - \delta_1) \left[ \frac{2\tau_2}{\delta_2} + \frac{5\tau_3}{\delta_3} + 1 + 5\nu \right] , \\ A_{0,-1,0} &= \frac{12}{\delta_1 \delta_2} (2+\delta_1 \omega) \tau_2 , \\ A_{0,0,-1} &= \frac{5}{2} \left[ \frac{8}{\delta_1 \delta_3} (2+\delta_1 \omega) + \frac{9}{\delta_2^2} \right] \tau_3 , \\ A_{0,-3,0} &= \frac{128}{45\delta_3^2} \tau_2 (\tau_2 - \delta_2) (\tau_2 - 2\delta_2) , \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system E

Discrete H<sub>3</sub> Hamiltonian

$$\begin{array}{rcl} A_{1,-1,0} & = & -\frac{24\tau_2}{\delta_1\delta_2} \ , \\ A_{1,0,-1} & = & -\frac{40\tau_3}{\delta_1\delta_3} \ , \\ A_{-1,-1,0} & = & -\frac{32}{15\delta_3}\tau_1\tau_2\left[\frac{\tau_2}{\delta_2}-\frac{20\tau_3}{\delta_3}-5(1+2\nu)\right] \ , \\ A_{-1,-2,0} & = & \frac{32}{15\delta_2\delta_3}\tau_1\tau_2(\tau_2-\delta_2) \ , \\ A_{-1,-1,1} & = & \frac{32}{15\delta_3}\tau_1\tau_2\left[\frac{\tau_2}{\delta_2}-\frac{10\tau_3}{\delta_3}-5(1+2\nu)\right] \ , \\ A_{-1,-1,-1} & = & -\frac{64}{3\delta_3^2}\tau_1\tau_2\tau_3 \ , \\ A_{-1,-2,1} & = & -\frac{32}{15\delta_2\delta_3}\tau_1\tau_2(\tau_2-\delta_2) \ , \end{array}$$

Marcos A. G. García The H<sub>3</sub> integrable system

<ロト <部ト < E > < E >

E

Discrete H<sub>3</sub> Hamiltonian

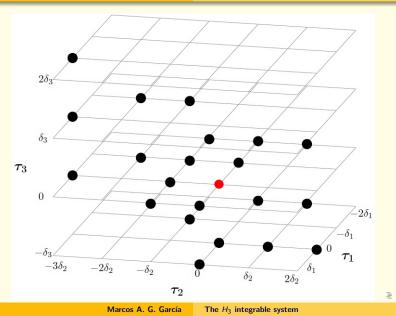
$$\begin{split} A_{-2,1,0} &= -\frac{48}{5\delta_2}\tau_1(\tau_1-\delta_1)\left[\frac{\tau_2}{\delta_2}+\frac{5\tau_3}{\delta_3}+1+5\nu\right] \\ A_{-2,-1,0} &= -\frac{48}{5\delta_2^2}\tau_2\tau_1(\tau_1-\delta_1) , \\ A_{-2,0,-1} &= -\frac{48}{\delta_2\delta_3}\tau_3\tau_1(\tau_1-\delta_1) , \\ A_{-2,1,-1} &= \frac{48}{\delta_2\delta_3}\tau_3\tau_1(\tau_1-\delta_1) , \\ A_{0,1,-1} &= -\frac{45\tau_3}{\delta_2^2} , \\ A_{0,2,-1} &= \frac{45\tau_3}{2\delta_2^2} , \\ A_{0,-3,1} &= \frac{256}{45\delta_3^2}\tau_2(\tau_2-\delta_2)(\tau_2-2\delta_2) , \\ A_{0,-3,2} &= \frac{128}{45\delta_3^2}\tau_2(\tau_2-\delta_2)(\tau_2-2\delta_2) . \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system

・ロト ・回 ト ・ヨト ・ヨト

E

#### Discrete H<sub>3</sub> Hamiltonian



Construction

## Quasi-exactly-solvable generalization

Among the eigenfunctions of the Hamiltonian  $h_{H_3}$  there is an infinite family of eigenfunctions depending on the variable  $\tau_1$ .

They are solutions of the equation

$$-h_1 \varphi \equiv -4 au_1 rac{\partial^2 \varphi}{\partial au_1^2} + (4\omega au_1 - 6(1+10
u)) rac{\partial \varphi}{\partial au_1} \; = \; \epsilon arphi \; .$$

Corresponding eigenfunctions are given by Laguerre polynomials:

$$\varphi_{n_1}(\tau_1) = L_{n_1}^{(1/2+15\nu)}(\omega\tau_1), \quad \epsilon_{n_1} = 4\omega n_1, \quad n_1 = 0, 1, 2, \dots$$

イロト イポト イヨト イヨト

 $\begin{array}{c} {\rm The} \ H_3 \ {\rm integrable} \ {\rm model} \\ {\rm The} \ h^{(3)} \ {\rm algebra} \\ {\rm The} \ discrete \ H_3 \ {\rm system} \\ {\rm Quasi-exactly-solvable} \ {\rm generalization} \\ {\rm Conclusion} \end{array}$ 

Construction

The operator  $h_1$  can be rewritten in terms of the generators of the Cartan subalgebra of sl(2) realized by the operators

$$J_k^+ = \tau_1^2 \frac{\partial}{\partial \tau_1} - k \tau_1 , \quad J_k^0 = \tau_1 \frac{\partial}{\partial \tau_1} - \frac{k}{2} , \quad J^- = \frac{\partial}{\partial \tau_1} ,$$

These generators have a common invariant subspace

$$\mathcal{P}_k = \langle au_1^p \mid 0 \leq p \leq k 
angle , \quad \dim \mathcal{P}_k = (k+1)$$

The operator  $h_1$  takes the sl(2)-Lie-algebraic form

$$h_1 = 4J_0^0 J^- - 4\omega J_0^0 + 6(1+10\nu)J^-$$

It preserves the infinite flag of spaces of polynomials

 $\mathcal{P}_0 \subset \mathcal{P}_1 \subset \mathcal{P}_2 \subset \cdots \subset \mathcal{P}_k \subset \cdots,$ 

and any eigenfunction is an element of the flag, and any eigenfunction is an element of the flag.

 $\begin{array}{c} {\sf The} \ H_3 \ {\sf integrable} \ {\sf model} \\ {\sf The} \ h^{(3)} \ {\sf algebra} \\ {\sf The} \ {\sf discrete} \ H_3 \ {\sf system} \\ {\sf Quasi-exactly-solvable} \ {\sf generalization} \\ {\sf Conclusion} \end{array}$ 

Construction

The operator  $h_1$  can be rewritten in terms of the generators of the Cartan subalgebra of sl(2) realized by the operators

$$J_k^+ = au_1^2 rac{\partial}{\partial au_1} - k au_1 \;, \quad J_k^0 = au_1 rac{\partial}{\partial au_1} - rac{k}{2} \;, \quad J^- = rac{\partial}{\partial au_1} \;,$$

These generators have a common invariant subspace

$$\mathcal{P}_k = \langle au_1^p \mid 0 \leq p \leq k 
angle , \quad \dim \mathcal{P}_k = (k+1)$$

The operator  $h_1$  takes the sl(2)-Lie-algebraic form

$$h_1 = 4J_0^0 J^- - 4\omega J_0^0 + 6(1+10\nu) J^-$$
.

It preserves the infinite flag of spaces of polynomials

$$\mathcal{P}_0 \subset \mathcal{P}_1 \subset \mathcal{P}_2 \subset \cdots \subset \mathcal{P}_k \subset \cdots,$$

and any eigenfunction is an element of the flag.

Construction

### Construction

• Look for the QES Hamiltonian in the form

$$\mathcal{H}^{(qes)} = \mathcal{H} + V^{(qes)}( au_1)$$

- Gauge rotate:  $h^{(qes)} = -2(\Psi_0)^{-1}(\mathcal{H}^{(qes)} E_0)(\Psi_0)$
- $h^{(qes)}$  should possess a  $au_1$ -depending family of eigenfunctions
- One obtains the equation

$$-h_1^{(qes)}arphi \equiv -4 au_1 rac{\partial^2 arphi}{\partial au_1^2} + (4\omega au_1 - 6(1+10
u)) rac{\partial arphi}{\partial au_1} + 2V^{(qes)}( au_1)arphi = \epsilon arphi$$

・ロット (四) (日) (日)

Construction

### Construction

• Look for the QES Hamiltonian in the form

$$\mathcal{H}^{(\mathit{qes})} = \mathcal{H} + V^{(\mathit{qes})}( au_1)$$

- Gauge rotate:  $h^{(qes)} = -2(\Psi_0)^{-1}(\mathcal{H}^{(qes)} E_0)(\Psi_0)$
- $h^{(qes)}$  should possess a  $\tau_1$ -depending family of eigenfunctions
- One obtains the equation

$$-h_{1}^{(qes)}\varphi \equiv -4\tau_{1}\frac{\partial^{2}\varphi}{\partial\tau_{1}^{2}} + (4\omega\tau_{1} - 6(1+10\nu))\frac{\partial\varphi}{\partial\tau_{1}} + 2V^{(qes)}(\tau_{1})\varphi = \epsilon\varphi$$

・ロト ・回ト ・ヨト ・ヨト

Construction

### Construction

• Look for the QES Hamiltonian in the form

$$\mathcal{H}^{(qes)} = \mathcal{H} + V^{(qes)}( au_1)$$

- Gauge rotate:  $h^{(qes)} = -2(\Psi_0)^{-1}(\mathcal{H}^{(qes)} E_0)(\Psi_0)$
- $h^{(qes)}$  should possess a  $\tau_1$ -depending family of eigenfunctions
- One obtains the equation

$$-h_1^{(qes)}arphi \equiv -4 au_1rac{\partial^2 arphi}{\partial au_1^2} + (4\omega au_1 - 6(1+10
u))rac{\partial arphi}{\partial au_1} + 2V^{(qes)}( au_1)arphi = \epsilon arphi$$

(日) (同) (E) (E) (E)

Construction

### Construction

• Look for the QES Hamiltonian in the form

$$\mathcal{H}^{(qes)} = \mathcal{H} + V^{(qes)}( au_1)$$

- Gauge rotate:  $h^{(qes)} = -2(\Psi_0)^{-1}(\mathcal{H}^{(qes)} E_0)(\Psi_0)$
- $h^{(qes)}$  should possess a  $\tau_1$ -depending family of eigenfunctions
- One obtains the equation

$$-h_1^{(qes)}arphi \equiv -4 au_1rac{\partial^2arphi}{\partial au_1^2} + (4\omega au_1 - 6(1+10
u))rac{\partialarphi}{\partial au_1} + 2V^{(qes)}( au_1)arphi = \epsilonarphi$$

(日) (同) (E) (E) (E)

Construction

• Let us gauge rotate  $h_1^{(qes)}$ :

$$h_1^{(sl(2)-qes)} = \tau_1^{-\gamma} \exp\left(\frac{a}{4}\tau_1^2\right) h_1^{(qes)} \tau_1^{\gamma} \exp\left(-\frac{a}{4}\tau_1^2\right)$$

• If 
$$V^{(qes)}$$
 is chosen of the form  

$$V^{(qes)} = \frac{1}{2} a^2 \tau_1^3 + a\omega \tau_1^2 - a\left(2k + 2\gamma + 15\nu + \frac{5}{2}\right) \tau_1 + \frac{\gamma(2\gamma + 30\nu + 1)}{\tau_1}$$
then  $h_1^{(sl(2)-qes)}$  is in  $sl(2)$ -Lie-algebraic form:  

$$h_1^{(sl(2)-qes)} = 4J_k^0 J^- - 4aJ_k^+ - 4\omega J_k^0 + 2(k + 4\gamma + 3(1 + 10\nu))J^-.$$

▲ロト ▲圖ト ▲屋ト ▲屋ト

Э

DQC

Construction

• Let us gauge rotate  $h_1^{(qes)}$ :

$$h_1^{(sl(2)-qes)} = \tau_1^{-\gamma} \exp\left(\frac{a}{4}\tau_1^2\right) h_1^{(qes)} \tau_1^{\gamma} \exp\left(-\frac{a}{4}\tau_1^2\right)$$

• If 
$$V^{(qes)}$$
 is chosen of the form  

$$V^{(qes)} = \frac{1}{2} a^2 \tau_1^3 + a\omega \tau_1^2 - a\left(2k + 2\gamma + 15\nu + \frac{5}{2}\right) \tau_1 + \frac{\gamma(2\gamma + 30\nu + 1)}{\tau_1}$$
then  $h_1^{(sl(2)-qes)}$  is in  $sl(2)$ -Lie-algebraic form:  

$$h_1^{(sl(2)-qes)} = 4J_k^0 J^- - 4aJ_k^+ - 4\omega J_k^0 + 2(k + 4\gamma + 3(1 + 10\nu))J^-.$$

▲ロト ▲圖ト ▲屋ト ▲屋ト

Э

DQC

Construction

The operator  $h_1^{(sl(2)-qes)}$  has  $\mathcal{P}_k$  as an invariant subspace, but it does not preserve a flag of spaces.

It has (k + 1) polynomial eigenfunctions of the form of polynomials of the degree k,

$$P_j^{(k)}(\tau_1) = \sum_{i=0}^k \gamma_i^{(j)} \tau_1^i , \quad j = 0, 1, 2, \dots ,$$

while other eigenfunctions are not polynomials.

イロト イヨト イヨト イヨト

Construction

sI(2)-quasi-exactly-solvable Hamiltonian associated with the root space  $H_3$ :

$$\begin{aligned} \mathcal{H}^{(qes)} &= \frac{1}{2} \sum_{k=1}^{3} \left[ -\frac{\partial^2}{\partial x_k^2} + \omega^2 x_k^2 + \frac{g}{x_k^2} \right] \\ &+ \sum_{\{i,j,k\}} \sum_{\mu_{1,2}=0,1} \frac{2g}{[x_i + (-1)^{\mu_1} \varphi_+ x_j + (-1)^{\mu_2} \varphi_- x_k]^2} \\ &+ \frac{1}{2} a^2 (\mathbf{x}^2)^3 + a \omega (\mathbf{x}^2)^2 - a \left( 2k + 2\gamma + 15\nu + \frac{5}{2} \right) \mathbf{x}^2 \\ &+ \frac{\gamma (2\gamma + 30\nu + 1)}{\mathbf{x}^2} , \end{aligned}$$

where  $\{i, j, k\} = \{1, 2, 3\}$  and all even permutations, and  $\mathbf{x}^2 = \sum_{i=1}^3 x_i^2$ .

Construction

We know (k + 1) eigenstates explicitly. Their eigenfunctions are of the form

$$\Psi_k(\mathbf{x}) = \Delta_1^{\nu} \Delta_2^{\nu} (\mathbf{x}^2)^{\gamma} \cdot P_k(\mathbf{x}^2) e^{-\frac{\omega}{2}\mathbf{x}^2 - \frac{\vartheta}{4}(\mathbf{x}^2)^2}$$

where  $P_k$  is a polynomial of degree k and  $g = \nu(\nu - 1) > -\frac{1}{4}$ .

イロト イヨト イヨト イヨト

## Conclusion

- An algebraic form for the  $H_3$  rational model exists. It acts on the spaces of polynomials  $\mathcal{P}_n^{(1,2,3)}$ ,  $n = 0, 1, 2, \ldots$ Eigenfunctions are elements of these spaces
- $\bullet$  An integral of motion exists. It has an algebraic form in  $\tau$  variables
- The hidden algebra of the  $H_3$  model is the  $h^{(3)}$  algebra, which has infinite dimension but is finitely generated
- It is possible to construct an isospectral discrete model and a quasi-exactly-solvable generalization
- Other integral(s) of motion has not been found yet
- Why different minimal flags are preserved by *h* and *f*?

$$\tau_1 = x_1^2 + x_2^2 + x_3^2$$

$$\begin{split} \tau_2 &= -\frac{3}{10} \left( x_1^6 + x_2^6 + x_3^6 \right) + \frac{3}{10} (2 - 5\varphi_+) \left( x_1^2 x_2^4 + x_2^2 x_3^4 + x_3^2 x_1^4 \right) \\ &+ \frac{3}{10} (2 - 5\varphi_-) \left( x_1^2 x_3^4 + x_2^2 x_1^4 + x_3^2 x_2^4 \right) - \frac{39}{5} \left( x_1^2 x_2^2 x_3^2 \right), \end{split}$$

Marcos A. G. García The H<sub>3</sub> integrable system

< □ > < □ > < □ > < □ > < □ > < □ > < □ >

$$\begin{aligned} \tau_{3} &= \frac{2}{125} \left( x_{1}^{10} + x_{2}^{10} + x_{3}^{10} \right) + \frac{2}{25} (1 + 5\varphi_{-}) \left( x_{1}^{8} x_{2}^{2} + x_{2}^{8} x_{3}^{2} + x_{3}^{8} x_{1}^{2} \right) \\ &+ \frac{2}{25} (1 + 5\varphi_{+}) \left( x_{1}^{8} x_{3}^{2} + x_{2}^{8} x_{1}^{2} + x_{3}^{8} x_{2}^{2} \right) \\ &+ \frac{4}{25} (1 - 5\varphi_{-}) \left( x_{1}^{6} x_{2}^{4} + x_{2}^{6} x_{3}^{4} + x_{3}^{6} x_{1}^{4} \right) \\ &+ \frac{4}{25} (1 - 5\varphi_{+}) \left( x_{1}^{6} x_{3}^{4} + x_{2}^{6} x_{1}^{4} + x_{3}^{6} x_{2}^{4} \right) \\ &- \frac{112}{25} \left( x_{1}^{6} x_{2}^{2} x_{3}^{2} + x_{2}^{6} x_{3}^{2} x_{1}^{2} + x_{3}^{6} x_{1}^{2} x_{2}^{2} \right) \\ &+ \frac{212}{25} \left( x_{1}^{2} x_{2}^{4} x_{3}^{4} + x_{2}^{2} x_{3}^{4} x_{1}^{4} + x_{3}^{2} x_{1}^{4} x_{2}^{4} \right). \end{aligned}$$

Back to presentation

< □ > < □ > < □ > < □ > < □ > < □ > < □ >

$$\begin{split} \mathcal{F} &= -\frac{1}{2} \left[ \frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left( \sin\theta \frac{\partial}{\partial\theta} \right) + \frac{1}{\sin^2\theta} \frac{\partial^2}{\partial\phi^2} \right] + \frac{2\nu(\nu-1)}{(s_\theta c_\phi + \varphi_+ s_\theta s_\phi + \varphi_- c_\theta)^2} \\ &+ \frac{2\nu(\nu-1)}{(s_\theta c_\phi - \varphi_+ s_\theta s_\phi + \varphi_- c_\theta)^2} + \frac{2\nu(\nu-1)}{(s_\theta c_\phi + \varphi_+ s_\theta s_\phi - \varphi_- c_\theta)^2} \\ &+ \frac{2\nu(\nu-1)}{(s_\theta c_\phi - \varphi_+ s_\theta s_\phi - \varphi_- c_\theta)^2} + \frac{2\nu(\nu-1)}{(s_\theta s_\phi + \varphi_+ c_\theta + \varphi_- s_\theta c_\phi)^2} \\ &+ \frac{2\nu(\nu-1)}{(s_\theta s_\phi - \varphi_+ c_\theta + \varphi_- s_\theta c_\phi)^2} + \frac{2\nu(\nu-1)}{(c_\theta + \varphi_+ s_\theta c_\phi + \varphi_- s_\theta s_\phi)^2} \\ &+ \frac{2\nu(\nu-1)}{(c_\theta - \varphi_+ s_\theta c_\phi + \varphi_- s_\theta s_\phi)^2} + \frac{2\nu(\nu-1)}{(c_\theta + \varphi_+ s_\theta c_\phi - \varphi_- s_\theta s_\phi)^2} \\ &+ \frac{2\nu(\nu-1)}{(c_\theta - \varphi_+ s_\theta c_\phi - \varphi_- s_\theta s_\phi)^2} + \frac{\nu(\nu-1)}{2s_\theta^2 c_\phi^2} + \frac{\nu(\nu-1)}{2s_\theta^2 s_\phi^2} + \frac{\nu(\nu-1)}{2c_\phi^2} \,. \end{split}$$

Back to presentation

Marcos A. G. García

The H<sub>3</sub> integrable system

DQC